

IN THE SPECIFICATION:

Please amend the specification by amending the Abstract as follows:

Tool guiding apparatus for guiding a tool along a path on a surface to be processed, said ~~wherein the~~ apparatus comprising ~~comprises~~ at least one path-defining means ~~definer~~ adapted to be attached to the surface, automatic tool actuating means ~~actuator~~ adapted to advance the tool along the path. Wherein the automatic tool actuation means ~~actuator~~ comprises a flexible force-transferring element comprising a first end and a second end, the first end being attached to the automatic tool actuation means ~~actuator~~ and the second end being attached to the tool.

Please amend the specification by amending the paragraph extending from page 8, line 10, to page 8, line 30, as follows:

Referring now to Fig. 1, the present invention relates to an apparatus 2 for guiding a tool 4 along a path 6. The apparatus is attached to a windscreen 8 which is attached to a car (not shown). The edge 10 of the windscreen 8 is glued to the car and the tool 4 is used to cut said glue. The apparatus comprises an automatic actuation means 12 comprising a motor 14 which is interconnected to a in-rolling-wheel 16 which rolls in a force-transferring element-here a belt 18-during operation of the apparatus 2. The automatic actuation means 12 comprises two positioning-wheels 20 which position the belt 18 in relation to the in-rolling-wheel 16. Furthermore, the automatic actuation means 12 comprises three moment arms 22 each of which is connected to a vacuum cup 24 in a first end and in a second end is connected to the motor 14. The apparatus 2 further comprises two path- defining means 26 each of which comprises a moment arm 22 in one end connected to a vacuum cup 24. In the other end the moment arm 22 is connected to a path-defining wheel 28. The wheel-surface 30 of the path-defining wheel 28 is covered with Velcro tape at the same time the belt-surface ~~32-31~~ is also covered with Velcros tape. Thus when the belt 18 is rolled in, the Velcro@ tape positions the belt in relation to the wheel so that the belt 18 is not stripped off during operation. Furthermore the path-defining wheel 28 comprises flanges 32 which also positions the belt 18 in the axial direction 34 of the path-defining wheel 28. The belt 18 comprises a hook 36 which during operation is attached to the tool 4. The tool 4 comprises a button

38 for activating the motor 14. The motor 14 comprises a power supply cable 40 which is adapted to be connected to the cigarette lighter plug of a car by means of a plug 42.

Please amend the specification by amending the paragraph extending from page 8, line 32, to page 9, line 3, as follows:

Fig. 2 shows a path-defining means 26 comprising two vacuum cups 24 comprising handles 44 which is used to create a vacuum between the a ~~bottom~~ **bottom** surface 46 and the windscreen 8. Furthermore the path-defining means 26 comprises a moment arm 22. In some embodiments the moment arm 22 is so long that it is possible to attach the path-defining means 26 to a surface of the windscreen which is substantially ~~plane~~ **planar**. This is desirable as it improves the ability of the vacuum cups 24 to maintain the vacuum. The wheel 28 may be pivotally connected to the moment arm 22 around the moment-arm-axis 48. The wheel-surface 30 has a surface which has high frictional properties e. g. the surface may be covered with Velcro® tape. Additionally the belt 18 is covered with Velcro® tape. The Velcro® tape may be provided on one side or on both sides of the belt 18 and on a part of the side(s) or on the entire side(s).

Please amend the specification by amending the paragraph extending from page 9, line 5, to page 9, line 9, as follows:

Fig 3. shows the tool 4 comprising fixture 37 having a button 38 which is used to activate the motor 14. The tool may comprise a wire (not shown) connected to the motor, but may also comprise a transmitter for wireless activation of the motor 14. A knife 50 is attached to the fixture 37 and may be changed if the screws **52** are removed. The tool 4 comprises a force transferring arm 54 comprising a hole 56 in which the hook may be inserted.